

Some PDE methods in mean field games theory
Cours FSMP

ALESSIO PORRETTA

Summary of unrecorded lesson: 30/03/2015

We recalled the notion of *renormalized solution* for second order problems. This notion, originally introduced by Di Perna and Lions [1] for transport equations, was later extensively used for second order problems with data belonging to L^1 , following [2]. In fact, in case of L^1 data, the usual H^1 energy setting is no more available for the solution, but remains valid for its truncations. However, compared with the transport equation, one needs to add a condition in the formulation in order to recover some crucial information on the set where the solution blows-up.

Let us recall briefly this definition for the case of L^1 -data. First we define, for $k > 0$, the truncation function

$$(1) \quad T_k(s) := \min(k, \max(s, -k)).$$

A function $v \in L^1(Q_T)$ is a renormalized solution to

$$(2) \quad \begin{cases} -v_t - \Delta v = f & \text{in } Q_T, \\ v(T) = v_T & \text{in } \Omega, \end{cases}$$

with, for example, Dirichlet conditions $v|_{\Sigma} = 0$, if

$$\begin{aligned} (i) \quad & T_k(v) \in L^2((0, T); H_0^1(\Omega)) \quad \forall k > 0 \\ (ii) \quad & \lim_{n \rightarrow \infty} \frac{1}{n} \int \int_{\{(t,x) : n < |v(t,x)| < 2n\}} |Dv|^2 dxdt = 0 \\ (iii) \quad & \begin{cases} -\partial_t S(v) - \Delta S(v) = S'(v)f - S''(v)|Dv|^2 & \text{in } Q_T \\ S(v)(T) = S(v_T) & \text{in } \Omega \end{cases} \end{aligned}$$

for every $S \in W^{2,\infty}(\mathbb{R})$ such that S' has compact support.

The regularity required for the truncations and the fact that S' has compact support give sense to the renormalized equation (iii) as usual, namely, $S(v) \in L^2((0, T); H_0^1(\Omega))$ and

$$\begin{aligned} & \int_0^T \int_{\Omega} S(v) \partial_t \varphi dxdt + \int_0^T \int_{\Omega} DS(v) D\varphi dxdt = \\ & \int_0^T \int_{\Omega} S'(v) f \varphi dxdt - \int_0^T \int_{\Omega} S''(v) |Dv|^2 \varphi dxdt + \int_{\Omega} S(v_T) \varphi(T) dx \end{aligned}$$

for every $\varphi \in C_c^\infty((0, T] \times \Omega)$.

Notice that condition (ii) preserves, asymptotically, the character of weak solution. Precisely, we define the following sequence of auxiliary functions:

$$(3) \quad S_n(r) = n S\left(\frac{r}{n}\right), \text{ where } S(r) = \int_0^r S'(r)dr, \quad S'(r) = \begin{cases} 1 & \text{if } |s| \leq 1 \\ 2 - |s| & \text{if } 1 < |s| \leq 2 \\ 0 & \text{if } |s| > 2 \end{cases}$$

so that S_n converges to the identity locally uniformly as $n \rightarrow \infty$. Since $S_n'' = -\frac{1}{n}\text{sign}(r)\chi_{\{n < |r| < 2n\}}$, if we take $S = S_n$ in (iii) and let $n \rightarrow \infty$, thanks to (ii) we recover the weak formulation.

If $\Omega = \mathbb{T}^N$, or if Neumann boundary conditions are required, the same definition extends replacing $H_0^1(\Omega)$ with $H^1(\Omega)$, and test functions are allowed to be in $C_c^\infty((0, T] \times \bar{\Omega})$.

The above renormalized setting extends to the study of the Fokker-Planck equation

$$(4) \quad \begin{cases} \partial_t m - \Delta m - \text{div}(m b) = 0, & \text{in } (0, T) \times \Omega, \\ m(0) = m_0 & \text{in } \Omega \end{cases}$$

whenever $b \in L^2(m)$, i.e. $m|b|^2 \in L^1(Q_T)$. This context for the study of (4) was extensively discussed in our previous lesson (26/03/2015).

A function $m \in L^1(Q_T)_+$ is a renormalized solution to (4), complemented for example with Dirichlet conditions $m|_\Sigma = 0$, if

$$(5) \quad T_k(m) \in L^2((0, T); H_0^1(\Omega)) \quad \forall k > 0$$

$$(6) \quad \lim_{n \rightarrow \infty} \frac{1}{n} \int \int_{\{n < |m| < 2n\}} |Dm|^2 dxdt = 0$$

$$(7) \quad \begin{cases} \partial_t S(m) - \Delta S(m) - \text{div}(S'(m)m b) + S''(m)|Dm|^2 + S''(m)mbDm = 0 & \text{in } Q_T, \\ S(m)(0) = S(m_0) & \text{in } \Omega, \end{cases}$$

for every $S \in W^{2,\infty}(\mathbb{R})$ such that S' has compact support.

Two main remarks are immediately in order. First of all, when we use (7) with $S = S_n$, defined in (3), we notice that

$$\|S_n''(m)|Dm|^2\|_{L^1} + \|S_n''(m)mbDm\|_{L^1} \leq \frac{C}{n} \int \int_{\{n < |m| < 2n\}} |Dm|^2 dxdt + C \int \int_{\{n < |m| < 2n\}} \frac{m^2}{n} |b|^2 dxdt \rightarrow 0$$

thanks to (6) and since $m|b|^2 \in L^1(Q_T)$. Therefore, a renormalized solution satisfies

$$(8) \quad \partial_t S_n(m) - \Delta S_n(m) - \text{div}(S_n'(m)m b) = \omega_n \quad \text{in } Q_T, \text{ and } \omega_n \xrightarrow{L^1(Q_T)} 0.$$

This implies that any bounded function in $L^2(0, T; H_0^1(\Omega))$ can be used as test function and in particular allows one to work with integral estimates, going through the renormalized formulation. Secondly, the renormalized formulation implies that $S(m) \in L^2(0, T; H_0^1(\Omega))$ with $S(m)_t \in L^2(0, T; H^{-1}(\Omega))$, which implies that $S(m) \in C^0([0, T]; L^1(\Omega))$ (see [3]). This will readily bring the continuity of m into L^1 .

Finally, the rest of the lesson is devoted to prove the existence and uniqueness of weak solutions to the mean field games system

$$\begin{cases} -\partial_t u - \nu \Delta u + H(t, x, Du) = F(t, x, m), & (t, x) \in (0, T) \times \Omega \\ \partial_t m - \nu \Delta m - \operatorname{div}(m H_p(t, x, Du)) = 0, & (t, x) \in (0, T) \times \Omega \\ m(0, x) = m_0(x), \quad u(T, x) = G(x, m(T)), & x \in \Omega \end{cases}$$

under general conditions on the functions f, G and H , and possibly different boundary conditions. The results presented are those contained in the work [3].

REFERENCES

- [1] R. J. Di Perna and P.L. Lions, *Ordinary differential equations, transport theory and Sobolev spaces*, Invent. math. **98** (1989), 511–547.
- [2] P.-L. Lions and F. Murat, *On renormalized solutions for nonlinear elliptic equations*, unpublished.
- [3] A. Porretta, *Weak solutions to Fokker-Planck equations and mean field games*, Arch. Rational Mech. Anal. 216 (2015), 1-62.